UBJECH

Embodied Al Empowers Humanoid to Accelerate Scenario, Applications

UBTECH ROBOTICS VP, Dr. Pang Jianxin

UBTECH

#### **Research History of Bipedal Humanoid Robots**



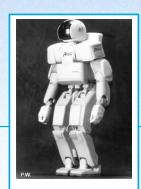
1969 Waseda University



1980 MIT-leg



1997 Spring Turkey MIT



1997 Honda P3



1997 HRP1 AIST



2000 Honda ASIMO



2008 MABEL



2025 Walker S2



2024 TianGong



2022 TeslaOptimus



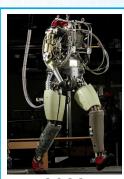
2019 UBTECH Walker



2013 Atlas Boston Dynamic

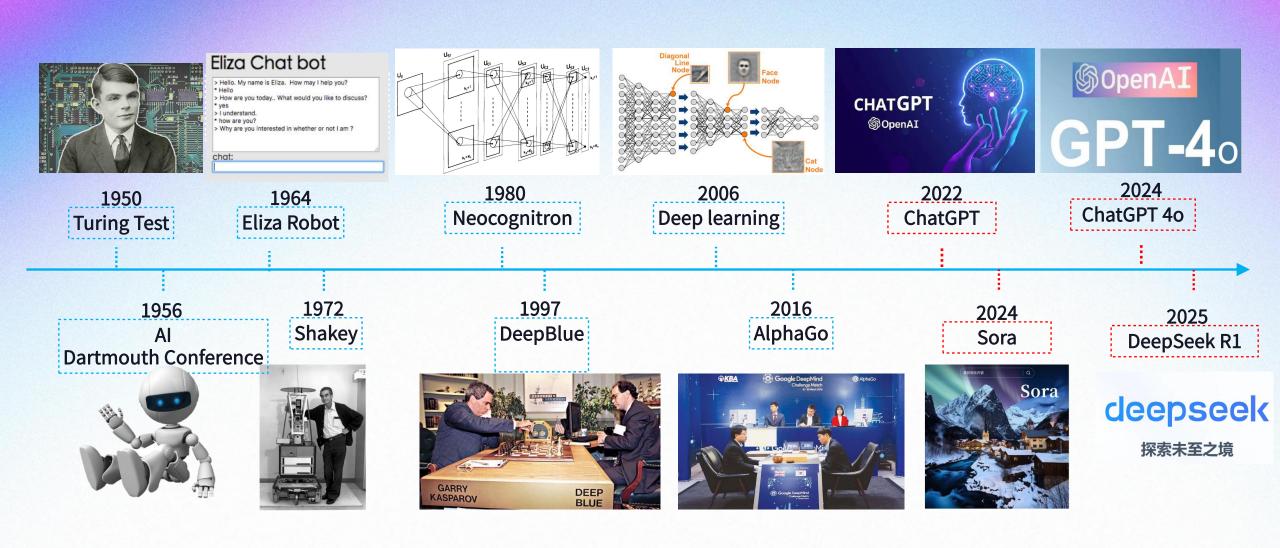


2012 M2V2 IHMC



2009 Petman Boston Dynamic

#### Al is advancing the intelligence of humanoid robots



### Humanoid robots are one of the ultimate forms of robots in the future



发展阶段	特点	应用	规模
初级机器人	基本不动+重复执行	机械手、轨道机器 人等	约 50 万个/年
中级机器人	行走+独立执行	清洁,环卫,仓储 搬运,室内外配送 机器人等	未来达到 1000 万/年
具身智能机器人	自主行走+自主执行	人形机器人等	未来与人类比例超过 1:1, 总量将达 100-200 亿

### Humans are accelerating into an AI era powered by humanoid robots

#### **The History of Science and Technological Progress**



The 1st Industrial Revolution Steam Technology

Mechanization



The 2nd Industrial Revolution Electrical Technology

**Electrification** 



The 3rd Industrial Revolution Information Technology

**Automation** 



The 4th Industrial Revolution
Ai-Quantum Technology

**Intelligentization** 

## Background of Labor Supply and Demand in China's Manufacturing Industry

By 2025, the shortage of manufacturing workers in China will be close to 30 million, with a shortage rate of 48%!

—— 《Guidelines for the Development Plan of Manufacturing Talents》 by the Ministry of HRSS、IIT、Edu.

Frontline workers face high labor intensity, which is the main reason for the labor shortage in the manufacturing industry.



Assembler: Repetitive tasks

Sorter: Frequent Bending



Inspector: Prolonged Standing

## Humanoid alleviating the contradiction between labor supply and demand in the manufacturing industry.

Traditional robots are widely used in structured environments and stille cannot replace frontline workers in unstructured environments.







Frontline workers in unstructured environments

Assembly/Sorting/ inspection/… ( Are still not replaced)

Humanoid can adapt to unstructured environments, which can alleviate the contradiction between frontline labor supply and demand

#### Humanoid

- Bipedal Locomotion
- Dual-Arm Manipulation
- Dexterous Hand



Industrial Scenarios



**Industry Humanoid** 



### Internationally, New Humanoid Robots for Industrial Scenarios Have Been Released

**2021** Agility Digit













2022 Tesla Optimus



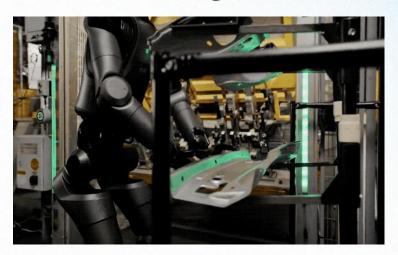
2023 Apptronik Apollo



2023 Figure 01



2024 Figure 02



### Internationally, New Humanoid Robots for Industrial Scenarios Have Been Released

**2024 Physical Intelligence** 

2024 BD Atlas

**2024** Tesla Optimus



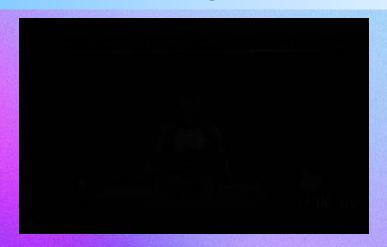




**2024 Sanctuary AI Phoenix** 

**2024 1X NEO Beta** 

2024 Tesla Optimus







## Governments Introduced Policies to Support the Development of the Humanoid Robot Industry



2023 MIIT 《Guiding on the Innovation and Development of Humanoid Robots》

"聚焦3C、汽车等制造业重点领域,提升人形机器人工具操作与任务执行能力,打造人形机器人示范产线和工厂,在典型制造场景实现深度应用。面向结构化生产制造环节,推动人形机器人在装配、转运、检测、维护等工序的应用和推广。面向非结构化生产制造环节,加强人形机器人与设备、人员、环境协作交互能力,支撑柔性化、定制化生产制造。"

Promote the Application and Popularization of Humanoid Robots in Processes Such as Assembly, Transfer, Inspection, Maintenance and Others.

#### **Embodied AI Development Elevated to Policy Priority**

### Embodied AI is listed in China's Government Work Report for the First Time

- 2025年政府工作报告中,首次将"具身智能"纳入国家未来产业发展规划, 培育生物制造、具身智能等未来产业成为重点。
- 国家工信部、教育部、科技部等部委密集出台相关政策,地方政府纷纷响应,通过深化人形智能机器人的产学研合作,推动具身智能科技创新和产业创新深度融合。

#### Ministry of Education States: AI Empowers the Development of a Strong Education Country

"推进人工智能全学段教育和全社会通识教育,源源不断培养高素质 人才。"

——习近平总书记4月25日在主持二十届中共中央政治局第二十次集体学习时强调

"人工智能是年轻的事业,也是年轻人的事业"。

——习近平总书记4月29日在上海考察时指出

#### China is accelerating Embodied AI policy support at both central and local levels.

时间	发布单位	政策名称
2023.1	工信部等十七部门	《"机器人+"应用行动实施方案》
2023.11	工业和信息化部	《人形机器人创新发展指导意见》
2024.1	工信部等七部门	《关于推动未来产业创新发展的实施意见》
2025.2	北京市科学技术委 员会、中关村科技 园区管理委员会等 3部门	《北京具身智能科技创新与产业培育行动计划 (2025-2027 年)》
2025.3	深圳市科技创新局	《深圳市具身智能机器人技术创新与产业发展行动计 划(2025—2027年)》

- 《教育强国建设规划纲要(2024—2035年)》《关于加快推进教育数字化的意见》中将人工智能与教育深度融合纳入教育强国建设战略布局,明确人工智能在教育数字化转型中的关键作用,为高校人工智能机器人专业发展提供了政策指引和依据。
- 教育部召开国家教育数字化战略行动2025年部署会,明确要培养更多既"懂技术",又"懂教育",更"懂人心"的教师,培育学生终身发展和社会发展所需要的正确价值观、必备品格和关键能力,共同提高人工智能素养,营造共生、共学、共研、共创的未来教育新格局。

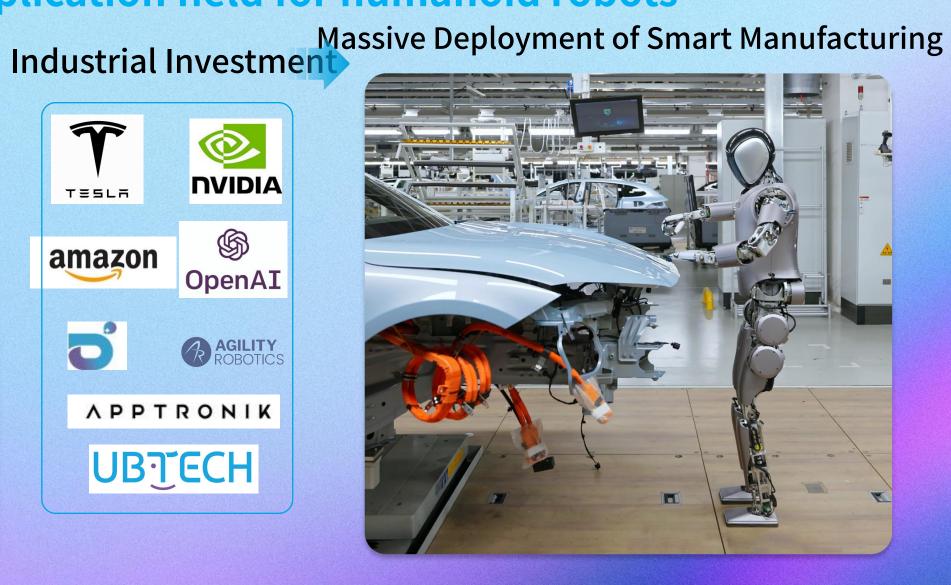
#### Industrial manufacturing will be the first large application field for humanoid robots

**Matket Space** 

**Policy Support** 







### Industrial manufacturing has emerged as the global battleground for humanoid robots



**Walker S2** 176cm / 73kg 2025















**Digit** 175cm / 48kg 2021





**Optimus** 173cm / 63kg 2024





**Apollo** 172cm / 72kg 2023





Figure 02 168cm / 70kg 2024



### Humanoid robots will perform highly repetitive, high-risk, and highly complex tasks.











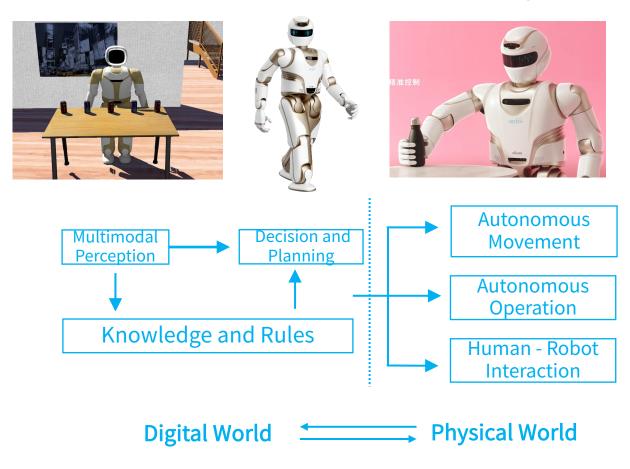




- Humanoid robots are the ultimate physical carrier of AI.
- They form a closed loop covering perception, decision-making, planning, execution, and learning.
- Multimodal large models enable humanoid robots to better understand the world.
- The combination of multimodal large models and humanoid robots
   represents a major step forward toward artificial general intelligence.

#### From Internet AI to Embodied AI

Jensen Huang: The Next Wave of Artificial Intelligence (AI) Will Be Embodied AI: Intelligent system capable of understanding, reasoning, and interacting with the physical world



From "Observational Learning" to "Experiential Learning" Actively perceive or interact with the world by doing tasks

#### **Multimodal LLM**

**Embodiment** 

**Embodied Evolution** 

**Embodied System** 

Robot

Machine Learning **Evolutionary Learning Computing Power** 

**Operating System** 

**Embodied** Perception

Computer Vision Speech Recognition **Multimodal Sensors**  **Embodied** Cognition

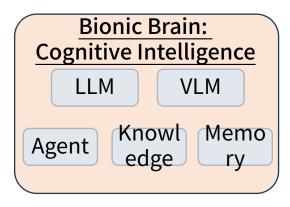
Cognitive Science **Decision - Making** Task Planning

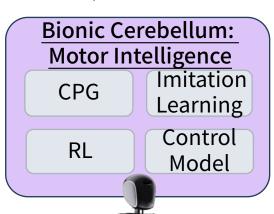
**Embodied** Behavior

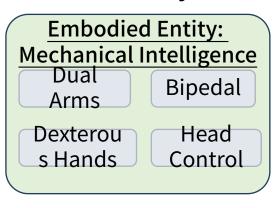
**Motion Planning Motion Control** Savety HRI

#### Embodied AI is the key to large-scale industrial implementation

Embodied AI technology covers key technology groups of the "brain" and "cerebellum", enabling humanoid robots to perceive, make decisions and act autonomously.









语音、视觉、文字、触觉、…

三维重建 动作映射 Real2Sim 实时仿真 环境模拟



数字孪生



决策

分拣、行走、搬运、交互、…

行动

域随机化 域自适应 Sim2Real

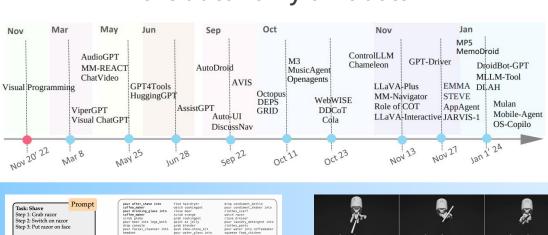
迁移学习

Navigation, Planning, ...

知识蒸馏

#### **Key Technology of Embodied AI - Large Model**

Multimodal LLMS continue to evolve, supporting the autonomy of robots



Task Shave
Sep 1: Geb racor
Sep 2: Switch on razor
Sep 3: Put racor on face
Task Apply lotion
Step 1:

Task Apply lotion
Step 1:

Frozen

Pre-Trained
Causal LLM

Squeeze out a glob of lotion

Task Squeeze out a glob of lotion



Motion control

SLAM



References: ICML 2022; CVPR 2023; ICLR 2024; arXiv: 2402.15116.

End2End large models for humanoid robots have become a hot topic

2024 Figure 01+Open Al



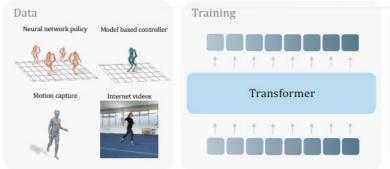
2024 NVIDIA GROOT



### **Key Technology of Embodied AI — Learning-Based Motion Control**

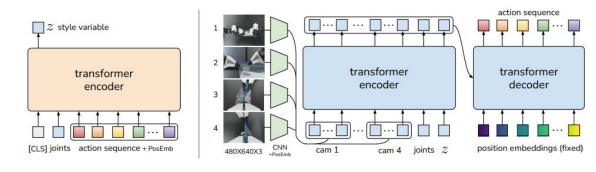
Learning-based motion control enables humanoid robots to better adapt to new environments and new tasks, while enhancing control robustness.

#### Walking--Digit Robot from UCB/OSU





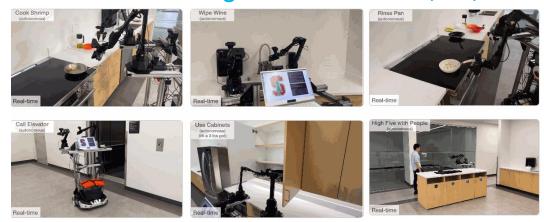
#### Manipulation--Aloha from Stanford Univisity



#### **Transformer**



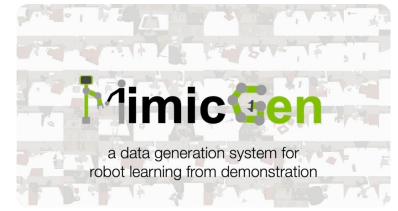
#### **Action Chunking with Transformers (ACT)**



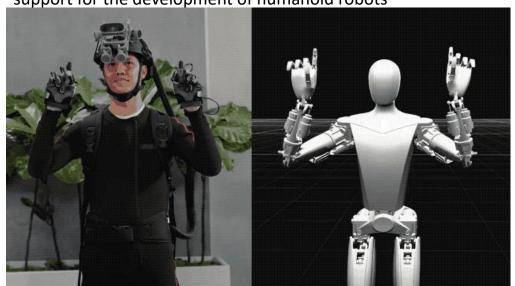
## **Key Technology of Embodied AI — Learning-Based Motion Control**



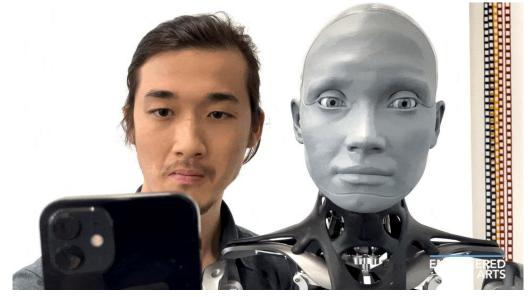




2024.7.31, NVIDIA's GR00T used Apple Vision Pro to solve the most painful data expansion difficulty in the robot field, providing more data support for the development of humanoid robots



Tesla leverages VR and teleoperation technology for robot imitation learning to conduct data collection.



Ameca robot performs facial expression imitation using video data.

References: SiGGRAPH2024; https://nerdist.com/article/robot-gets-more-realistic-expressions-engineering-arts-ameca/

#### Key Technology of Embodied AI—from VLM to VLA





Close bottom drawer



Knock Coke can over



Move orange can near green rice chip bag



Move Red Bull can near blueberry RXBAR

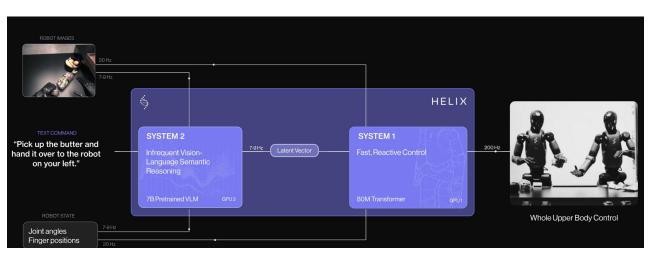


Pick green rice chip bag from middle drawer and place on countertop



Place 7 Up can upright

References: Stanford、UC Berkeley、TRI、Deepmind和MIT: "OpenVLA: An Open-Source Vision-Language-Action Model", https://www.figure.ai/news/helix





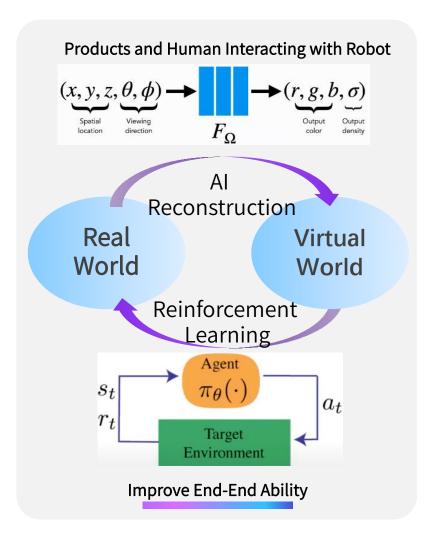




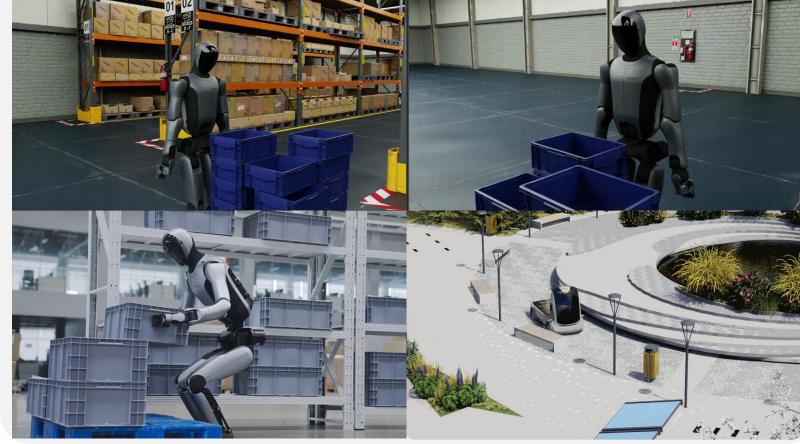


#### Al Agent-Based Simulation System UNDERS2

Simulate and generate diverse scenes for robots at low cost (environments, objects, and changes)



Simulate changes in environment: illumination/weather/object textures/occlusion/dynamic scenes









# UBTech's self-developed humanoid robot's brain "Thinker" has won 4 global No.1.

MS COCO detection challenge- Segmentation Mask
MS COCO detection challenge - Bounding Box
RoboVQA and Egoplan-bench2



#### **UBTECH Humanoid Robots Scene Exploration**



The practical training of humanoid robots in new energy vehicle factories.



**Box Carrying** 





**Multi-Robot Collaboration** 

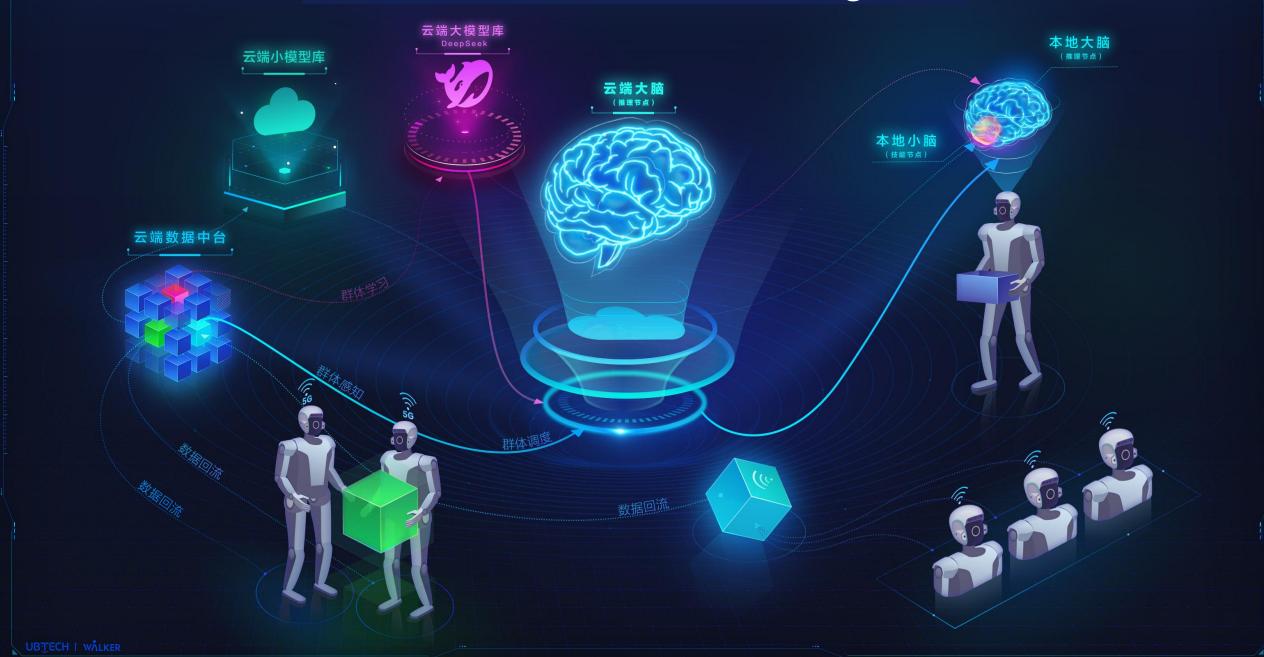


**Screw Tightening and Gluing** 

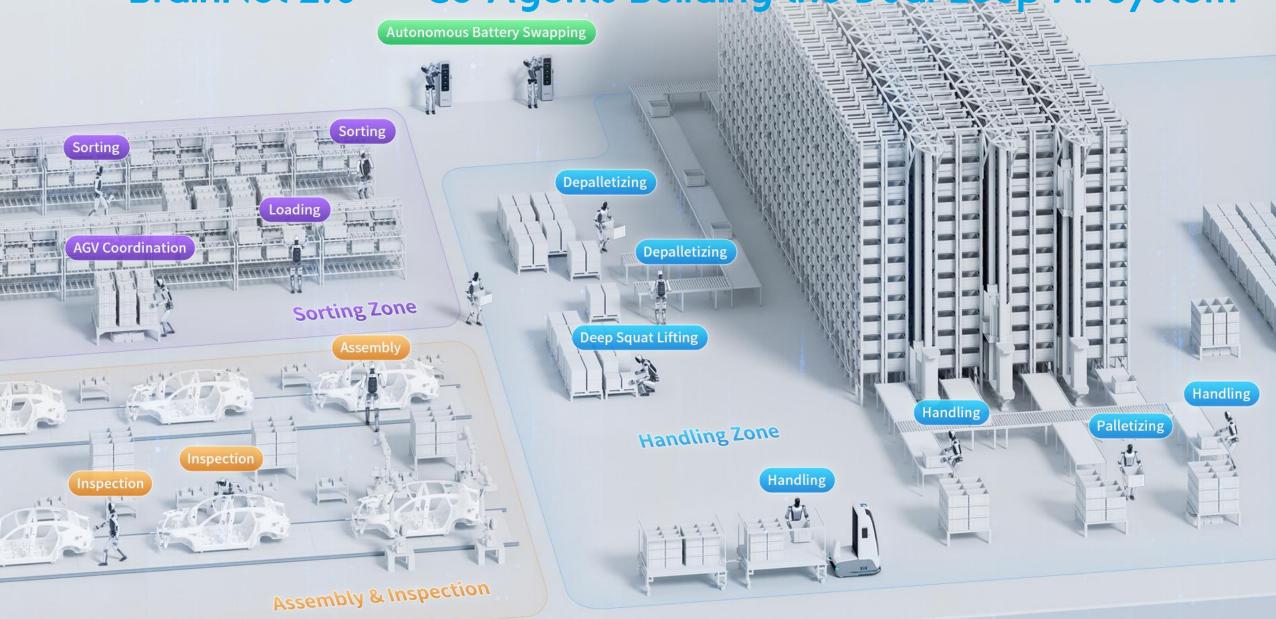


Multimodal LLMl General-Purpose Services

#### **UBTech BrainNet & Swarm Intelligence**



Production Line Task-Driven Swarm Intelligence for Humanoid "BrainNet 2.0" + Co-Agents Building the Dual-Loop AI System





### UBTECH

Humanoid Robot Industrial Application Solution

**Our Partners** 



























## Scenario data, as a key asset, supports the application and implementation of humanoid robot technology.

#### **Scenario Applications**

Commercial Services

household Services

**Industrial Manufacturing** 

Extreme Operations

•••••

#### **Bionic Brain**

LLM

VLM

Agent

Knowl edge

Memo ry

#### **Bionic Cerebellum**

CPG

RL

RL

C M

#### **Embodiment**

**Dual Arms** 

**Bipedal** 

Dexterous Hands Head Control

感知	决策	行动

语音、视觉、文字、触觉……

导航、规划……

分拣、行走、搬运、交互……

#### Real2Sim

三维重建 | 动作映射 实时仿真 | 环境模拟

#### 场景数据生产

数字孪生

#### Sim2Real

域随机化 | 域自适应 迁移学习 | 知识蒸馏



### Governments Are Actively Promoting Data Collection and Training Centers, with Industrial Scenarios Emerging as a Key Focus Area

#### Data Collection Centers Are Being Promoted Across the Country



Shanghai Guodi Center: Embodied Intelligence Training Ground



Beijing Guodi Center: Embodied Intelligence Training Ground



Beijing Humanoid Robot Data Training Center



Yangtze River Delta Intelligent Robot Training Center

#### **Policy**

时间	发布单位	政策名称
2023.10	工业和信息化部	《人形机器人创新发展指导意见》
2024.12	国家发改委、数据局等	《关于促进数据产业高质量发展的指导意见》
2025.2	北京市科学技术委员会、中关村科技园 区管理委员会等	《北京具身智能科技创新与产业培育行动计划(2025-2027 年)》
2025.3	深圳市科技创新局	《深圳市具身智能机器人技术创新与产业发展行动计划(2025—2027年)》

#### Data Collection Centers Support the Rapid Implementation of Industrial Scenario Applications Through Scenario Data Production, Model Training.

#### Market **Demand**

新能源汽车 传统机械制造 3C制造 物流 纺织

#### 5G网络

#### 第一类数采空间

用于产线级场景、多机协同场景、多类型任务场景的数采任务 模拟场景 + 遥操作设备 + 人形机器人 + 采集工程师 + 云平台

# 1

#### 第二类数采空间

全流程仟务场景的数采仟务 ·遥操作设备 + 人形机器人 + 采集工程师 + 云平台

#### 场景配置区

模块化元素 高仿真度元素

#### 数据管理区

存储服务器 数据平台 数据标注员

#### 机器人维保区

机器人易损件 标定工具 维保人员

#### 仿直与训练区

训练服务器 仿直训练平台 数据挖掘人员

### industry

Support the

**Embodied AI** 

#### PB级垂域数据集

每年采集不少于 100万条多模态数据

#### 垂域小模型库

每年训练不少于 100种小模型技能

100台人形工业数采中心

#### 数据采集中心作业场景













规模数据采集基地



海量数据赋能模型训练



强干扰反应式规划能力



工业场景数据采集

# In the Implementation of Industrial Scenarios, Data Collection Tasks Have Spurred the Emergence of Numerous Emerging Jobs

Simulation

Pre-sales Solution

Manager for

Embodied AI

Robots

Data Simulation Engineer

Al Model Training Engineer Governance

Embodied AI Data
Collection
Engineer

Embodied Data
Annotation
Engineer

Embodied Data Audit Engineer

Applica ntion

Embodied AI Robot Application Engineer

Embodied AI Robot Operation and Maintenance Engineer

More Jobs .....

## Humanoid robots are going to the stage of industrialization and implementation







**Industrial Manufacturing** 

**Commercial Services** 

household Services

Limited and Known Tasks in Structured or Semi-Structured Environments



Needs for Companion and Conversation



Complex Dynamic Scenarios
Involving Physical Contact with
Humans

## The commercial service scenario is the fastest market for humanoid robots.

















## Humanoid robots will enter households in two phases





**Companion Scenario** 



**Service Scenario** 

#### Dream with Robots

#### Mission

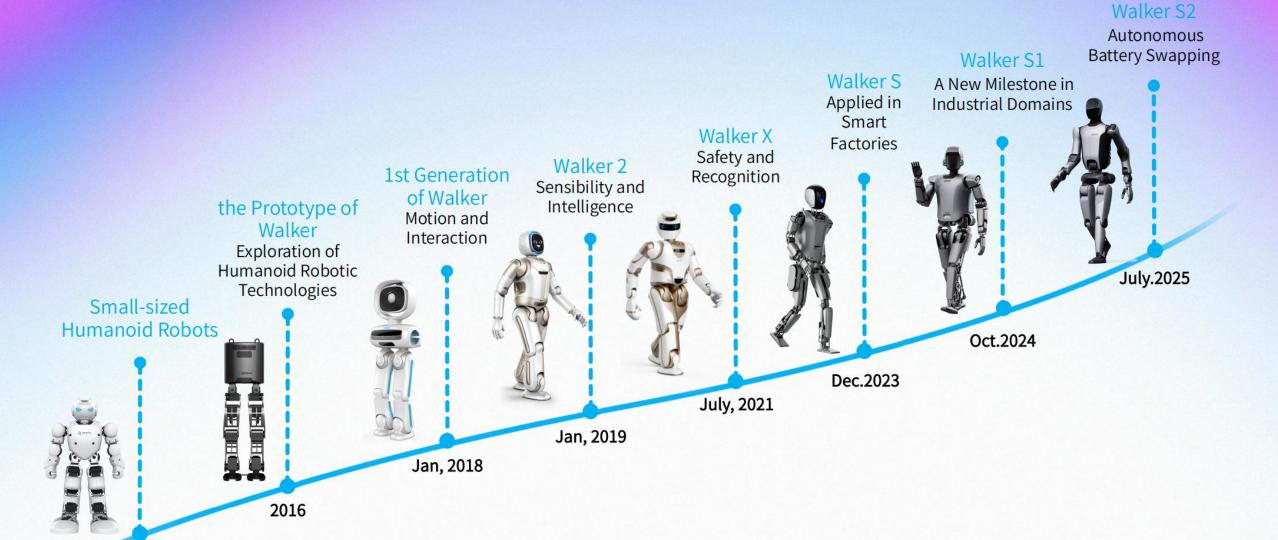
To bring intelligent robots into every family to make everyday life more convenient and intelligent.

#### Vision

To build an intelligent ecosystem integrating hardware, software, services, and operations using intelligent robots as carriers and AI technology as the core.



#### Development of UBTECH Humanoid Robots



2012 (Produced in 2014)

#### UBTECH's Self-Developed Full-Stack Humanoid Robot Technologies

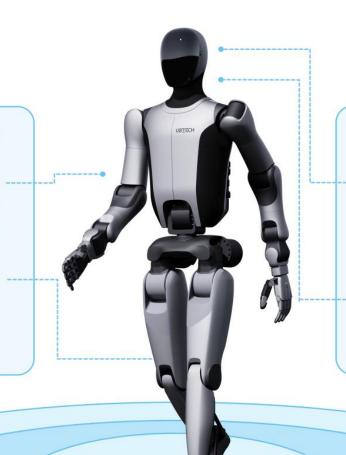
#### Humanoid Hardware-Control Technologies

#### **High Performance Servo Actuators**

Advanced Lightweight Integrated Joint Design High Accuracy, High Stability for Large Torque High Density, Cost-effective for Medium to Small Torque

#### Motion Planning & Control

Robust Gait Planning and Whole-Body Control Algorithm Dextrous Manipulation Planning and Servo Control Algorithm Safe Human-Robot Interaction and Compliant Control Algorithm



#### AI Technologies

#### **Human-like Brain Function**

Large Visual-Language Models
Multimodal Perception & Interaction
AIGC Simulation Platform
Semantic VSLAM

#### Human-like Cerebellum Function

Reinforcement learning Imitation learning

System Integration Technologies SLAM & Autonomous Technologies Modularity

**Robot Operating System 2.0** 

Scalability

Visual Servo Manipulation & HRI

GUI & Self-state Report

**Integrated Humanoid Robot Technologies** 

#### Commercialization in Various Industries Based on Our Full-stack Humanoid Robotic Technologies

Al Education Robotic Products and Solutions Smart Logistics
Robotic Products
and Solutions

Smart Elderly Care Solutions Service Smart Robotic Products and Solutions Consumer-level Robotic Products and Solutions



































Dream with Robots